

# Using CHiLL and CUDA-CHiLL PAID IME

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# Long List of Collaborators

- Original Developer: Chun Chen
- Current Utah students:
  - Khalid Ahmad, Payal Nandy, Tharindu Rusira, Tuowen Zhao
- Ongoing collaborations:
  - LBNL: Protonu Basu, Brian van Straalen, Sam Williams
  - ANL: Prasanna Balaprakash, Hal Finkel, Paul Hovland
  - Arizona: Michelle Strout, Mahdi Mohammadi
  - Boise State: Cathie Olschanowsky
  - Intel: Anand Venkat
- Utah former students
  - Shreyas Ramalingam, Axel Rivera, Amit Roy, Gabe Rudy, Huihui Zhang
- USC students and collaborators:
  - Jacque Chame, Malik Khan, Jaewook Shin

Which version would you prefer to write?

## /\* Laplacian 7-point Variable-Coefficient Stencil

```

for (k=0; k<N; k++)
    for (j=0; j<N; j++)
        for (i=0; i<N; i++)
            temp[k][j][i] = b * h2inv * (
                beta_i[k][j][i+1] * ( phi[k][j][i+1] - phi[k][j][i] )
                -beta_i[k][j][i] * ( phi[k][j][i] - phi[k][j][i-1] )
                +beta_j[k][j+1][i] * ( phi[k][j+1][i] - phi[k][j][i] )
                -beta_j[k][j][i] * ( phi[k][j][i] - phi[k][j-1][i] )
                +beta_k[k+1][j][i] * ( phi[k+1][j][i] - phi[k][j][i] )
                -beta_k[k][j][i] * ( phi[k][j][i] - phi[k-1][j][i] ) );

```

```

/* Helmholtz */
for (k=0; k<N; k++)
    for (j=0; j<N; j++)
        for (i=0; i<N; i++)
            temp[k][j][i] = a * alpha[k][j][i] * phi[k][j][i] -
                temp[k][j][i];

```

```

/* Gauss-Seidel Red Black Update */
for (k=0; k<N; k++)
    for (j=0; j<N; j++)
        for (i=0; i<N; i++){
            if ((i+j+k+color)%2 == 0 )
                phi[k][j][i] = phi[k][j][i] - lambda[k][j][i] *
                    (temp[k][j][i] - rhs[k][j][i]);}

```

**Code A:** miniGMG baseline smooth operator  
approximately 13 lines of code

## Memory Hierarchy

```
Prefetch
```

## Data staged in registers/buffers

## AVX SIMD intrinsics

## Parallelism

Parallel Wavefronts:  
Reduce sweeps over 3D grid

## Nested OpenMP and MPI

const \_m256d phi\_07 = \_mm256\_insert128\_p0\_d(m  
const \_m256d phi\_09 = \_mm256\_insert128\_p0\_d(m  
const \_m256d temp\_12 = \_mm\_load\_pd(phi+i:j) + 14  
temp\_15 = \_mm\_load\_pd(phi+i:j) + 16

**Code B:** miniGMG optimized smooth operator  
approximately 170 lines of code

 THE  
UNIVERSITY  
OF UTAH

# And GPU Code?

**Code C:** miniGMG optimized smooth operator for GPU, 308 lines of code for just kernel



# Code B/C is not Unusual

- Performance portability?
  - Particularly across fundamentally different CPU and GPU architectures
- Programmer productivity?
  - High performance implementations will require low-level specification that exposes architecture
- Software maintainability and portability?
  - May require multiple implementations of application

## Current solutions

- Follow MPI and OpenMP standards
  - Same code unlikely to perform well across CPU and GPU
  - Vendor C and Fortran compilers not optimized for HPC workloads
- Some domain-specific framework strategies
  - Libraries, C++ template expansion, standalone DSL
  - Not **composable** with other optimizations

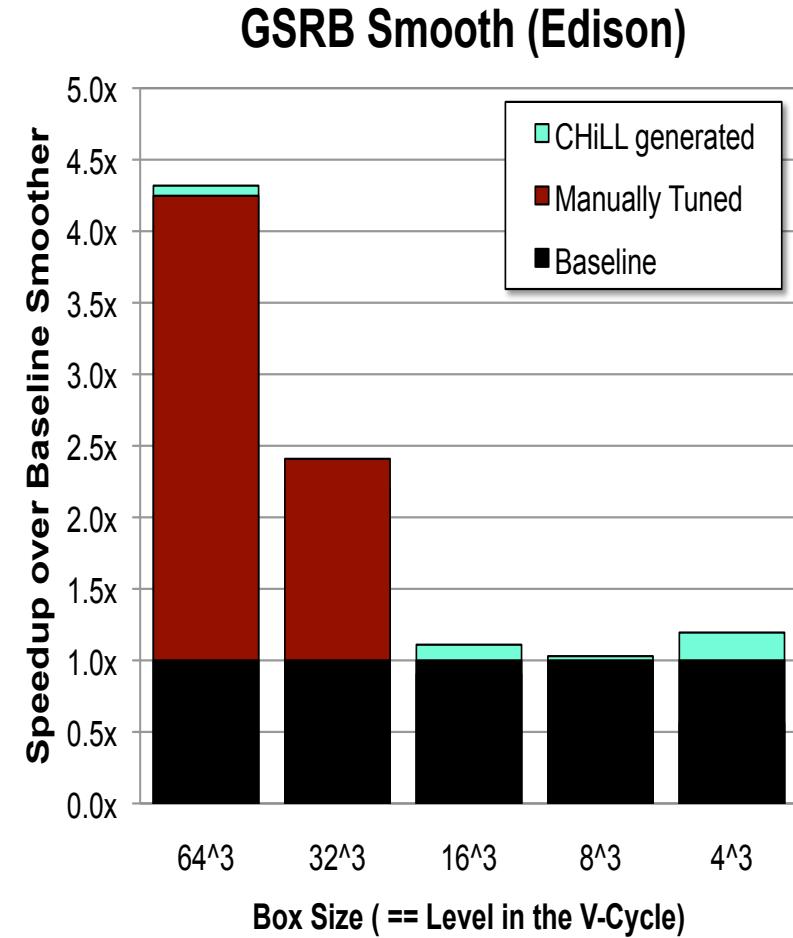
# CHiLL Approach

- CHiLL: compiler optimization framework with ***domain-specific specialization***
  - Target is loop-based scientific applications
  - ***Composable*** transformations
- Optimization strategy can be specified or derived with ***transformation recipes***
  - Also optimization parameters exposed
- ***Autotuning***
  - Systematic exploration of alternate transformation recipes and their optimization parameter values
  - Search technology to prune combinatorial space

Automate process of generating Code B from Code A.

# Example Result: Sometimes Code A+CHiLL beats Code B!

- miniGMG w/CHiLL
  - Fused operations
  - Communication-avoiding waveform
  - **Parallelized (OpenMP)**
- **Autotuning** finds the best implementation for each box size
  - waveform depth
  - nested OpenMP configuration
  - inter-thread synchronization (barrier vs. point-to-point)
- For fine grids (large arrays) CHiLL attains nearly a **4.5x speedup** over baseline



Collaborators: Protonu Basu, Sam Williams, Brian van Straalen, Lenny Oliker,  
Phil Colella (LBNL) [HIPC13][WOSC14][IPDPS15][PARCO17]

# CHiLL Research

- Develop autotuning and code generation experiments with application partners
  - Stencils and multi-grid
  - Tensor contraction
  - Sparse matrix codes
- DOE Partnerships to speed up HPC applications
  - SciDAC SUPER
- PAID (Blue Waters)
- Exascale Computing Project

# CHiLL in PAID

- CHiLL: Autotuning loop transformation and code generation framework
- CUDA-CHiLL: Thin layer for CUDA

Application and PI	What we did	Impact
CPPTRAJ, Cheatham	Targeted GPU	29X Speedup on key computation, Integrated into production code
MILC QCD, Gottlieb	Improved OpenMP Reduction	2.4X Speedup on KNL
FTDT, Simpson	Thread-level Parallelism (CUDA+OpenMP)	Ongoing, 6.5X Speedup compared to sequential

# Polyhedral Transformation and Code Generation

## Stage 1 :

*Loop Bounds  
Extraction & Iteration  
Space Construction*

Input Code:  
`for(i=0; i < n; i++)  
s0: a[i]=b[i];`



Iteration Space (IS):  
 $s0 = \{[i] : 0 \leq i \leq n\}$

## Stage 2 :

*Transformation ( $T$ )*

Input IS:  
 $\{[i] : 0 \leq i \leq n\}$

$$T = \{[i] \rightarrow [i+4]\}$$



Output IS:  
 $\{[i] : 4 \leq i \leq n + 4\}$

## Stage 3 :

*Code generation*

Update statement  
macro with  $T_{inv}$ . Apply  
Polyhedra Scanning

$$T_{inv} = \{[i] \rightarrow [i-4]\}$$



Output Code:  
`for(i=4; i < n+4; i++)  
s0: a[i-4]=b[i-4];`

# Using CHiLL

Input

Source Code:  
example.c

Transformation  
Recipe:  
example.py

*Different recipes  
and parameters  
produce different  
output for  
performance  
portability.*

*SuperScript encodes complete search space*

Autotuning Search

*External Search  
Frameworks:  
Active Harmony,  
Orio, OpenTuner*

# Example CHiLL Superscripts for Code A

```
original()  
skew ([0,1,2,3,4,5], 2, [3,1])  
permute ([2,1,3,4])
```

```
partial_sums(0)  
partial_sums(5)
```

```
fuse ([0,1,2,3,4,5,6,7,8,9], 4)
```

```
omp_par_for(4,3)
```

```
original()  
skew ([0,1,2,3,4,5], 2, [3,1])  
permute ([2,1,3,4])
```

```
partial_sums(0)  
partial_sums(5)
```

```
fuse ([0,1,2,3,4,5,6,7,8,9], 4)
```

```
@begin_param_region  
param(x,enum,[1,2,3,4,6,12])  
param(y,enum,[1,2,3,4,6,12])  
constraint(x*y==12)  
omp_par_for(x,y)  
@end_param_region
```

```
import chillsuper as cs  
cs.generate_parameter_domain('superscript')
```

<https://github.com/TharinduRusira/CHiLLsuper>

# CHiLL Interactive Demos

1. Shift example
2. MILC example
3. MRIQ example (CUDA)
4. Smooth in miniGMG

# MILC and CHiLL

- Dslash operator dominates execution
- Different data layout/implementation for each new architecture, architecture-specific

```
for (it1=0; it1<4; it1++) {  
    for (it2=0; it2<3; it2++) {  
        for (it3=0; it3<3; it3++) {  
            tc_real[it3] += ta_real[it1][it3][it2] *  
                tb_real[it1][it2];  
            tc_imag[it3] += ta_real[it1][it3][it2]  
                * tb_imag[it1][it2];  
            tc_real[it3] -= ta_imag[it1][it3][it2]  
                * tb_imag[it1][it2];  
            tc_imag[it3] +=  
                ta_imag[it1][it3][it2] *  
                tb_real[it1][it2];  
        } } }
```

Code A: 3x3 complex matrix-vector multiply  
7 lines of code.

```
for(n=0;n<4;n++,mat++){  
    switch(n){  
        case(0): b=b0; break; case(1): b=b1; break; case(2): b=b2; break;  
        case(3): b=b3; break; default: b = 0; }  
    br=b->c[0].real; bi=b->c[0].imag;  
    a0=mat->e[0][0].real; a1=mat->e[1][0].real; a2=mat->e[2][0].real;  
    c0r += a0*br; c1r += a1*br; c2r += a2*br;  
    c0i += a0*bi; c1i += a1*bi; c2i += a2*bi;  
    a0=mat->e[0][0].imag; a1=mat->e[1][0].imag; a2=mat->e[2][0].imag;  
    c0r -= a0*bi; c1r -= a1*bi; c2r -= a2*bi;  
    c0i += a0*br; c1i += a1*br; c2i += a2*br;  
    br=b->c[1].real; bi=b->c[1].imag; a0=mat->e[0][1].real; a1=mat->e[1][1].real;  
    c0r += a0*br; c1r += a1*br; c2r += a2*br;  
    c0i += a0*bi; c1i += a1*bi; c2i += a2*bi;  
    a0=mat->e[0][1].imag; a1=mat->e[1][1].imag; a2=mat->e[2][1].imag;  
    c0r -= a0*bi; c1r -= a1*bi; c2r -= a2*bi;  
    c0i += a0*br; c1i += a1*br; c2i += a2*br;  
    br=b->c[2].real; bi=b->c[2].imag; a0=mat->e[0][2].real; a1=mat->e[1][2].real;  
    a2=mat->e[2][2].real; c0r += a0*br; c1r += a1*br; c2r += a2*br;  
    c0i += a0*bi; c1i += a1*bi; c2i += a2*bi; a0=mat->e[0][2].imag;  
    a1=mat->e[1][2].imag; a2=mat->e[2][2].imag; c0r -= a0*bi; c1r -= a1*bi;  
    c2r -= a2*bi; c0i += a0*br; c1i += a1*br; c2i += a2*br;  
} c->c[0].real = c0r; c->c[0].imag = c0i; c->c[1].real = c1r; c->c[1].imag = c1i;  
c->c[2].real = c2r; c->c[2].imag = c2i;}  
c->c[0].real = c0r; c->c[0].imag = c0i; c->c[1].real = c1r; c->c[1].imag = c1i;  
c->c[2].real = c2r; c->c[2].imag = c2i;}
```

Code B: Example implementation in MILC  
72 lines of code.

# MRIQ Optimized Example

```
1 permute(0,{"j","i"})
2 tile_by_index({"j"},{TI},{l1_control="jj"}, {"jj","j","i"})
3 normalize_index("j")
4 normalize_index("i")
5 tile_by_index({"i"},{TJ},{l1_control="ii",l1_tile="i"},
               {"jj","ii","j","i"})
6 cudaize("kernel_GPU", {x=N,y=N,z=N,Qr=N,Qi=N,kVals=M},
          {block={"jj"},thread={"j"}})
5 copy_to_shared("tx","kVals",1)
6 copy_to_texture("kVals")
7 copy_to_registers("ii","x")
8 copy_to_registers("ii","y")
9 copy_to_registers("ii","z")
10 copy_to_registers("ii","Qi")
11 copy_to_registers("ii","Qr")
```

(Output:  
See file)

From Khan et al., A script-based autotuning compiler system to generate high-performance CUDA code. *ACM Trans. Archit. Code Optim.* 9, 4, Article 31 (January 2013).

# Conclusion

- Autotuning compiler technology useful to achieve performance portability on new architectures!
- First time working with a facilities team
- Software improvements
  - Test cases, doxygen, github, updates to manual
  - Abstraction that separates from compiler AST
- New Research
  - Data layout optimization (MILC)
  - C++ iterators and vector library support (CPPTRAJ)
  - Specialization of coefficient matrix (FTDT)